

chapter! 3.

The static Magnetic field  
OR  
Magnetostatic fields

- (1) charges moving with constant velocity  
(i.e. constant current (or Direct current)  
in current carrying wires.
- (2) Permanent magnets.

Produces steady magnetic field  
(i.e. constant with time)

Steady Magnetic field  
governed by

- ↓  
Biot-Savart's law  
— General  
— applicable for any current distribution.  
— Similar to coulomb's law in electrostatics

- ↓  
Amperes Circuit Law  
— For only symmetrical current distribution.  
— Similar to Gauss's law in Electrostatics.

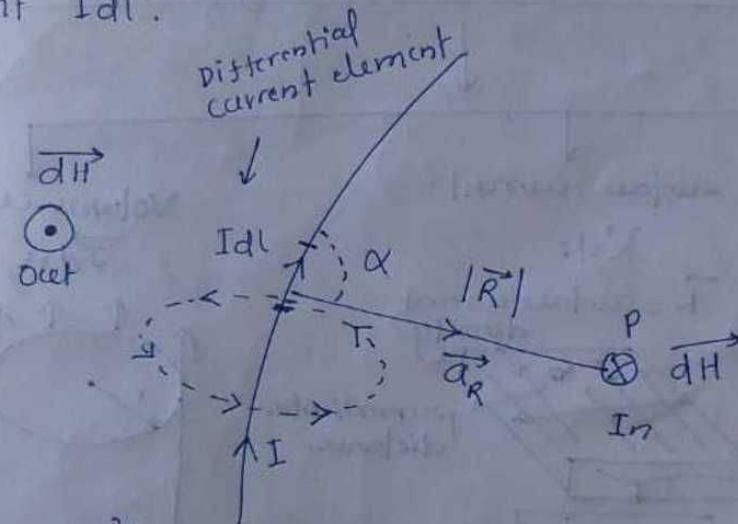
Applications :

- ① Development of motors
- ② Microphone
- ③ Telephone ringers
- ④ Transformers
- ⑤ High speed Velocity Device
- ⑥ particle accelerators like cyclotrons.
- ⑦ Electromagnetic pump & so on ...

Note: Magnetic field Intensity  $\vec{H} \approx$  Electric field intensity  $\vec{E}$ .  
 (Wb/m<sup>2</sup>) Magnetic flux density  $\vec{B} \approx$  Electric flux Density  $\vec{D}$  (C/m<sup>2</sup>)

### Biot Savart's law

states that "The differential magnetic field Intensity  $|d\vec{H}|$  produced at a point P by the differential current element  $|Idl|$  is proportional to the product  $|Idl|$  &  $\sin\alpha$  of the angle between the element & the line joining P to the element & is inversely proportional to the square of the distance R between P & the element  $|Idl|$ .



A/ Biot Savart's law.  
 current element =  $|Idl|$  - (magnitude)

$$\text{so, } dH \propto \frac{|Idl \sin\alpha|}{R^2} - \text{(magnitude)}$$

$$dH = \frac{K |Idl| \sin\alpha}{R^2}$$

where; K = constant of proportionality

$$K = \frac{1}{4\pi} \text{ in S.I unit}$$

$$\therefore dH = \frac{|Idl| \sin\alpha}{4\pi R^2} \text{ (magnitude form)}$$

Note:

Direction Using Right hand Rule



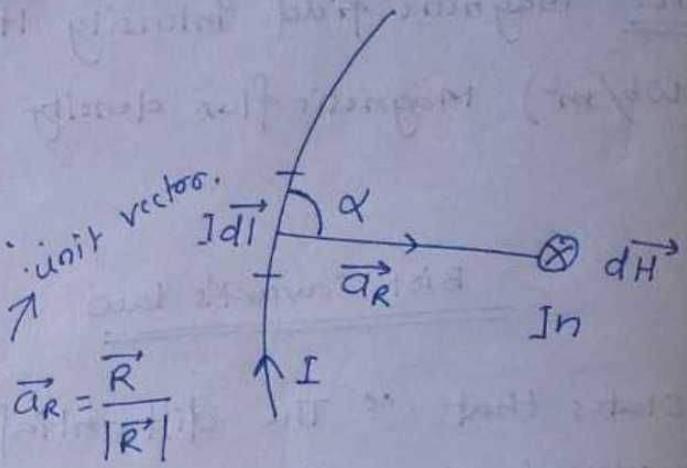
$\vec{H}$  (o.f) is out-

(conventional representation)

$\vec{H}$  (o.f) is IN

In Vector form:

$$d\vec{H} = \frac{Id\vec{l} \times \vec{a}_R}{4\pi R^2}$$

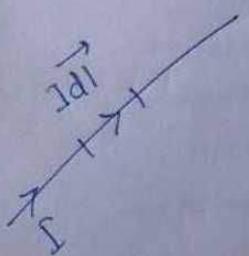


$$d\vec{H} = \frac{Id\vec{l} \times \vec{R}}{4\pi R^3}$$

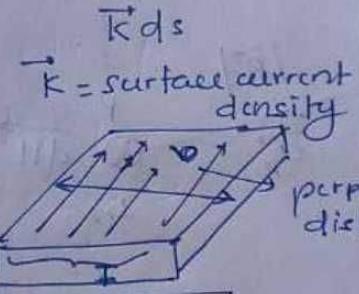
### current Distribution in Magneto-statics



Line current



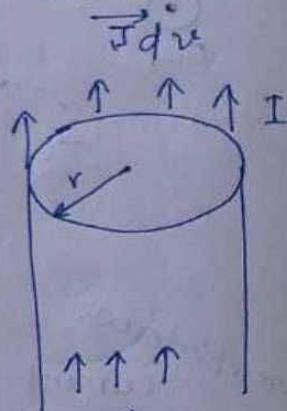
surface current



$$K = \frac{I}{b}$$

b = perpendicular to direction of current

Volume current



$$J = \text{Volume current Density}$$

Note: Surface current density ( $K$ ) = for current flowing on the surface of a conductor & is defined for uniform current density

$$I = Kb$$

For Non uniform Surface current density:

$$I = \int K dN$$

where  $dN$  = Differential element of path across which current is flowing.

$\Rightarrow$  current element can be expressed in terms of :-

$$\vec{Idl} \equiv \vec{K}ds \equiv \vec{J}dv$$

————— x —————

$\Rightarrow$  According to Biot-Savart's law :

$$\vec{H} = \int_L \frac{\vec{Idl} \times \vec{a}_R}{4\pi R^2} = \int_L \frac{\vec{Idl} \times \vec{R}}{4\pi R^3} \quad \dots \quad (\text{Line current})$$

$$\vec{H} = \int_S \frac{\vec{K}ds \times \vec{a}_R}{4\pi R^2} = \int_S \frac{\vec{K}ds \times \vec{R}}{4\pi R^3} \quad \dots \quad (\text{Surface current})$$

$$\vec{H} = \int_V \frac{\vec{J}dv \times \vec{a}_R}{4\pi R^2} = \int_V \frac{\vec{J}dv \times \vec{R}}{4\pi R^3} \quad \dots \quad (\text{Volume current})$$

$\Rightarrow$  Magnetic field due to straight conductor

$\Rightarrow$  Field at point P due to a straight filamentary conductor: —

consider AB finite length of conductor.

$idl$ : small current element

current I flows from A; ( $\alpha = \alpha_1$ )  
to B; ( $\alpha = \alpha_2$ )

from Biot-Savart's law

$$d\vec{H} = \frac{Idl \times \vec{R}}{4\pi R^3}$$

from Fig:  $d\vec{l} = dz \vec{a}_z$

$$\vec{R} = p\vec{a}_\rho - z\vec{a}_z$$

so,  $d\vec{l} \times \vec{R} = (dz \vec{a}_z) \times (p\vec{a}_\rho - z\vec{a}_z)$

$$= pdz \vec{a}_\phi$$

$$d\vec{H} = \frac{IP dz \vec{a}_\phi}{4\pi p^3 \cosec^3 \alpha}$$

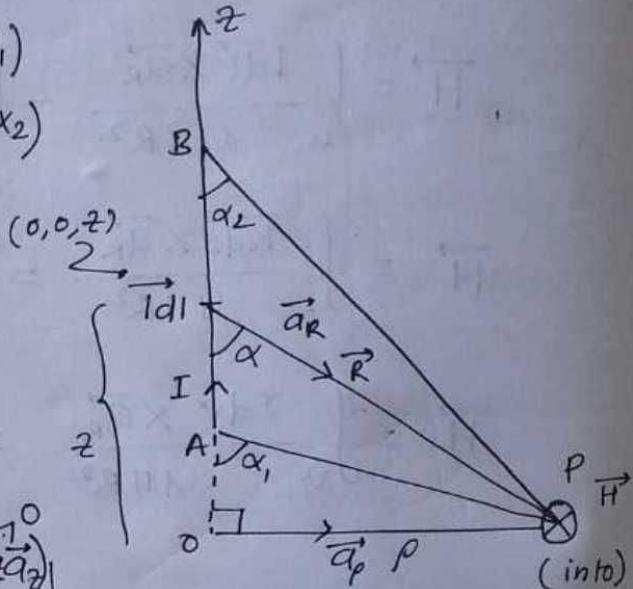
To get total

$$\vec{H} = \int \frac{IP (-P \cosec^2 \alpha) d\alpha}{4\pi (P^3 \cosec^3 \alpha)} \vec{a}_\phi$$

$$= -\frac{I}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{P^2 \cosec^2 \alpha d\alpha}{P^3 \cosec^3 \alpha} \vec{a}_\phi$$

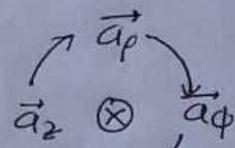
$$= -\frac{I}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{1}{P \cosec \alpha} d\alpha \vec{a}_\phi$$

$$\boxed{\vec{H} = -\frac{I}{4\pi P} [\cos \alpha_2 - \cos \alpha_1] \vec{a}_\phi}$$



$$z\vec{a}_z + \vec{R} = p\vec{a}_\rho$$

$$\vec{R} = p\vec{a}_\rho - z\vec{a}_z$$



$$\tan \alpha = \frac{p}{z}$$

$$z = p \frac{1}{\tan \alpha} = p \cot \alpha$$

$$dz = -P \cosec^2 \alpha d\alpha$$

$$R^2 = (P^2 + (-z)^2)$$

$$R^2 = (P^2 + P^2 \cot^2 \alpha)$$

$$R^2 = P^2 (1 + \cot^2 \alpha)$$

$$= P^2 \left( 1 + \frac{\cot^2 \alpha}{\sin^2 \alpha} \right)$$

$$R^2 = P^2 \left( \frac{\sin^2 \alpha + \cot^2 \alpha}{\sin^2 \alpha} \right)$$

$$R^2 = P^2 \frac{1}{\sin^2 \alpha} = P^2 \cosec^2 \alpha$$

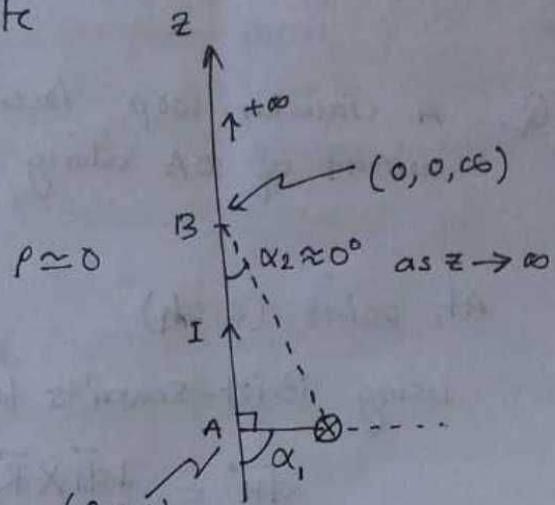
$$\text{or } R = P \cosec \alpha$$

CASE-I

conductor in semi-Infinite

$$\alpha_1 = 90^\circ \quad \alpha_2 \approx 0^\circ$$

$$\vec{H} = \frac{I}{4\pi\rho} \vec{a}_\phi$$



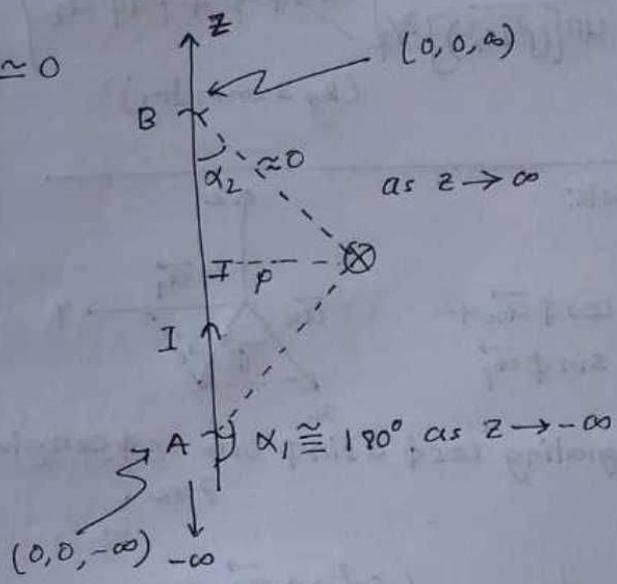
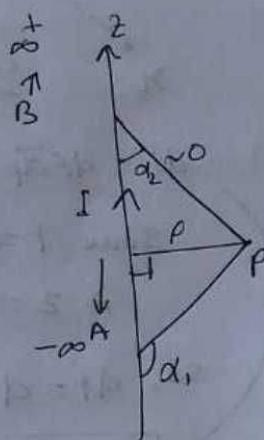
CASE-II

Infinite Lenz

$$A(0,0,-\infty) \quad \& \quad B(0,0,\infty)$$

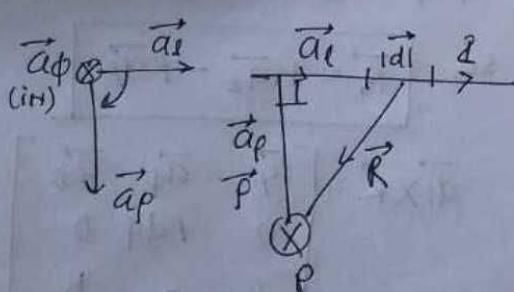
$$\alpha_1 \approx 180^\circ, \quad \alpha_2 \approx 0^\circ$$

$$\vec{H} = \frac{I}{2\pi\rho} \vec{a}_\phi \quad \rho \approx 0$$



Note: Simple formula to find  $\vec{a}_\phi$

$$\vec{a}_\phi = \vec{a}_z \times \vec{a}_p$$



$\vec{a}_e$  = unit vector along line current

$\vec{a}_p$  = unit vector  $\perp$  along the line current to the field point.

$\Rightarrow$  Magnetic field due to circular loop

Q. A circular loop located on  $x^2 + y^2 = 9$ ,  $z=0$  carries a direct current of 10A along  $\vec{a}_\phi$ . Determine  $\vec{H}$  at  $(0, 0, 4)$  &  $(0, 0, -4)$

At, point  $(0, 0, h)$

using Biot-Savart's law

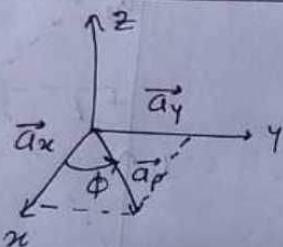
$$d\vec{H} = \frac{I d\vec{l} \times \vec{R}}{4\pi R^3}$$

$$\vec{dH} = \frac{I}{4\pi[(\rho^2+h^2)]^{3/2}} \left\{ \rho d\phi \vec{a}_\rho + \frac{1}{\rho} d\phi \vec{a}_z \right\}$$

(By symmetry)

Note:

$$\vec{a}_\rho = \cos\phi \vec{a}_x + \sin\phi \vec{a}_y$$

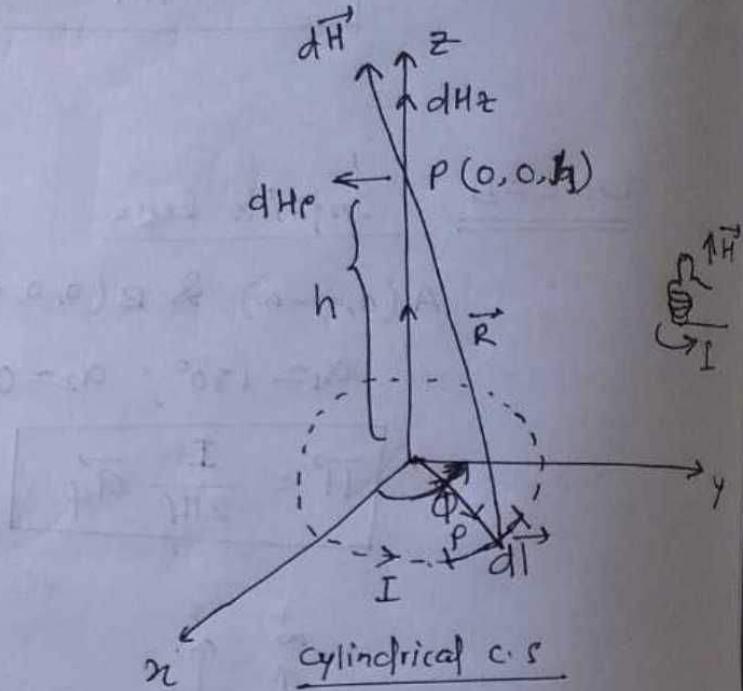


Integrating  $\cos\phi$  &  $\sin\phi$  over  $0 \leq \phi \leq 2\pi$  gives zero.

$$\therefore \vec{H} = \int d\vec{H} \vec{a}_z = \int \frac{I \rho^2 d\phi \vec{a}_z}{4\pi[\rho^2+h^2]^{3/2}} = \frac{I \rho^2 \vec{a}_z}{4\pi[\rho^2+h^2]^{3/2}} \int_0^{2\pi} d\phi$$

$$\vec{H} = \frac{I \rho^2 (2\pi) \vec{a}_z}{4\pi[\rho^2+h^2]^{3/2}}$$

$$\text{or } \vec{H} = \frac{I \rho^2 (2\pi) \vec{a}_z}{2\pi 2 [\rho^2+h^2]^{3/2}}$$



$$d\vec{l} = d\rho \vec{a}_\rho + \rho d\phi \vec{a}_\phi + dz \vec{a}_z$$

since  $\rho = \text{constant}$

&  $z = 0$  for given loop

$$\text{so, } d\rho = dz = 0$$

$$\boxed{d\vec{l} = \rho d\phi \vec{a}_\phi}$$

From Fig:

$$\rho \vec{a}_\rho + \vec{R} = h \vec{a}_z$$

$$\text{so, } \boxed{\vec{R} = h \vec{a}_z - \rho \vec{a}_\rho}$$

$$\vec{dI} \times \vec{R} = \begin{bmatrix} \vec{a}_\rho & \vec{a}_\phi & \vec{a}_z \\ 0 & \rho d\phi & 0 \\ -\rho & 0 & h \end{bmatrix}$$

$$\boxed{\vec{dI} \times \vec{R} = \rho h d\phi \vec{a}_\rho + \rho^2 d\phi \vec{a}_z}$$

$$\boxed{R = \sqrt{\rho^2 + h^2}}$$

$$\boxed{\vec{H} = \frac{I\rho^2 \vec{a}_z}{2[\rho^2 + h^2]^{3/2}}}$$

Magnetic field intensity at point  $(0, 0, h)$  due to circular loop (at  $z=0$ ) having radius  $\rho$ .

(a) At  $(0, 0, 4)$

put  $I = 10A$ ,  $h = 4$  To find  $\rho \Rightarrow x^2 + y^2 = \rho^2$   
 $x^2 + y^2 = (3)^2$  ... given

$$\vec{H}(0, 0, 4) = \frac{10(3)^2 \vec{a}_z}{2[9+16]^{3/2}}$$

$$= 0.36 \vec{a}_z \text{ A/m}$$

(b) At  $(0, 0, -4)$ ,  $h = -4$

$$\vec{H} = \frac{I\rho^2 \vec{a}_z}{2(\rho^2 + h^2)^{3/2}}, I = 10A, \rho = 3$$

$$H = \frac{10(3)^2 \vec{a}_z}{2[9+(-4)^2]^{3/2}}$$

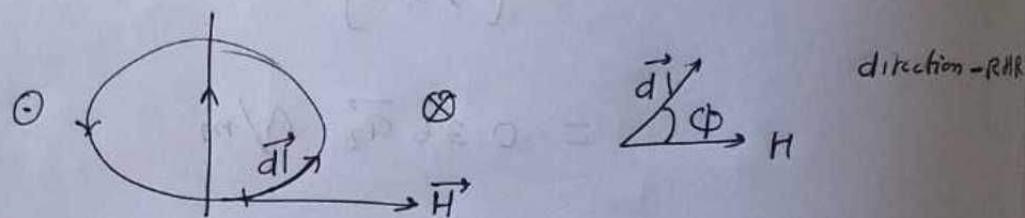
$$= 0.36 \vec{a}_z \text{ A/m.}$$

Ampere's Circuit law - OR int. of Maxwell's equation.

"Ampere's circuit law, states that the line integral of  $\vec{H}$  around a closed path is the same as the net current  $I_{enc}$  enclosed by the path"

$$\oint_L \vec{H} \cdot d\vec{l} = I_{enc} \quad - \text{Integral form}$$

→ "The circulation of  $\vec{H}$  equals  $I_{enc}$ ;"



using stokes theorem.

$$\int_S (\nabla \times \vec{H}) \cdot d\vec{s} = I_{enc}$$

$$\oint_L \vec{H} \cdot d\vec{l} \approx \oint_S \vec{H} \cdot d\vec{s}$$

$\nabla \rightarrow \text{curl}$

Also,  $I_{enc} = \int_S \vec{J} \cdot d\vec{s}$

$$\nabla \times \vec{H} = \vec{J} \rightarrow \text{3rd maxwell's equat'}$$

→ Ampere's law in differential form (or point form)

Note: Since,  $\nabla \times \vec{H} \neq 0$ , a magneto static field is not conservative.

## Applications of Ampere's law

(1) used to determine  $\vec{H}$  for symmetrical current distribution such as

- \* Infinite line current
- \* Infinite sheet of current
- \* Infinitely long coaxial transmission line.

} Apply  
 $\oint \vec{H} \cdot d\vec{l} = I_{enc}$

(2) For symmetrical current distribution,  $\vec{H}$  is either parallel or perpendicular to  $d\vec{l}$ .

### Infinite line current

To determine  $\vec{H}$ , Ampere's circuit law is applied

- consider closed path  $\approx$  Amperean path
- which shows that  $\vec{H}$  is constant as  $\rho$  is constant.

Note: Amperean path is analogous to Gaussian surface.

$$\oint \vec{H} \cdot d\vec{l} = I$$

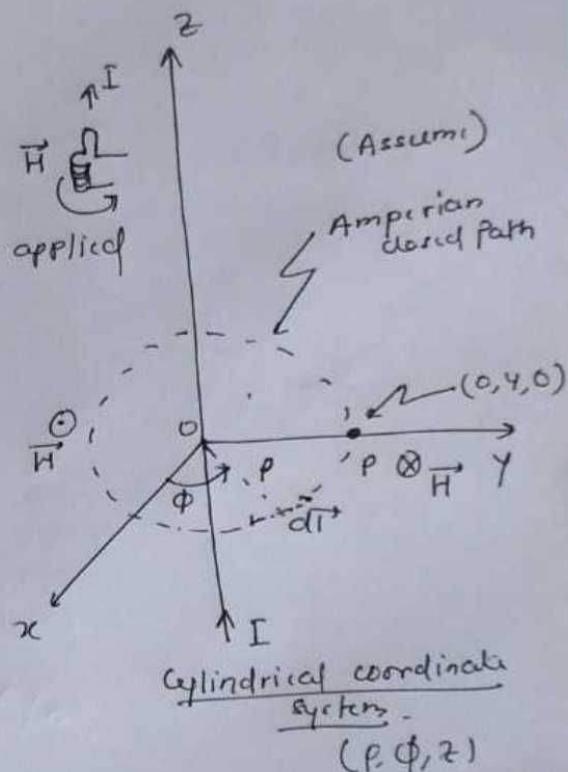
$$\oint H_\phi \vec{a}_\phi \cdot \rho d\phi \vec{a}_\phi = I$$

$$H_\phi \rho \oint_0^{2\pi} d\phi = I \quad (0 \leq \phi \leq 2\pi)$$

$$H_\phi \rho (2\pi) = I$$

$$H_\phi = \frac{I}{2\pi\rho} \quad \dots \text{ (magnitude)}$$

$$\vec{H} = \frac{I}{2\pi\rho} \vec{a}_\phi \quad \dots \text{ (Vector form)}$$



$$\vec{H} = H_\rho \vec{a}_\rho + H_\phi \vec{a}_\phi + H_z \vec{a}_z$$

$$d\vec{l} = d\rho \vec{a}_\rho + \rho d\phi \vec{a}_\phi + dz \vec{a}_z$$

Also,  $\rho = \text{constant}$   
 $z = 0$  for point P

$$\therefore d\rho = dz = 0$$

$$d\vec{l} = \rho d\phi \vec{a}_\phi$$