

(5)

$$\nabla \times \vec{E} = -N \frac{d\vec{B}}{dt}$$

if $N=1$

$$\boxed{\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}}$$

→ Maxwell's 2nd eqⁿ for static field time varying field (differential form or point form)

$$\boxed{\vec{B} = \mu \vec{H}} \rightarrow \text{magnetic flux Density}$$

$$\therefore \boxed{\vec{D} = \epsilon \vec{E}} \rightarrow \text{electric flux Density}$$

(3) Ampere's law :

closed loop

It states that line integral of tangential component of magnetic field is equal to current enclosed by that closed loop.

$$\oint_L \vec{H} \cdot d\vec{l} = I_{enc} \quad \text{--- (1)}$$

Let \vec{J}_c be conduction current Density ($\frac{A}{m^2}$)

$$I = \int_S \vec{J}_c \cdot d\vec{s} \quad \text{--- (2)}$$

$$\boxed{\oint \vec{H} \cdot d\vec{l} = \int_S \vec{J}_c \cdot d\vec{s}}$$

Maxwell's 3rd equation (integral form)

For Time Varying field

$$\oint \vec{H} \cdot d\vec{l} = \int_S (\vec{J}_c + \vec{J}_D) \cdot d\vec{s}$$

$\vec{J}_c =$ conduction current Density ($\sigma \vec{E}$)

↳ conductivity of the conduction

$\vec{J}_D =$ Displacement current Density ($\frac{\partial \vec{D}}{\partial t}$)

⇒ For differential form,
from Stokes's theorem

(6)

$$\int_S (\nabla \times \vec{H}) \cdot d\vec{s} = \int_S \vec{J}_c \cdot d\vec{s}$$

$\nabla \times \vec{H} = \vec{J}_c$

 (static field)

For time Varying field,

$\nabla \times \vec{H} = \vec{J}_c + \vec{J}_0$

 → Maxwell's 3rd eqⁿ.
(differential form)

(4) Isolated magnetic monopole does not exist:

Total magnetic flux passing through closed surface is always zero.

$\oint \vec{B} \cdot d\vec{s} = 0$

 ⇒ Maxwell's 4th equation
(integral form)

applying Divergence theorem: $\oint \vec{B} \cdot d\vec{s} = \int_V (\nabla \cdot \vec{B}) dv$

$$\Rightarrow \int_V (\nabla \cdot \vec{B}) dv = 0$$

$\Rightarrow \nabla \cdot \vec{B} = 0$

 ⇒ Maxwell's 4th equation is
(Differential form)