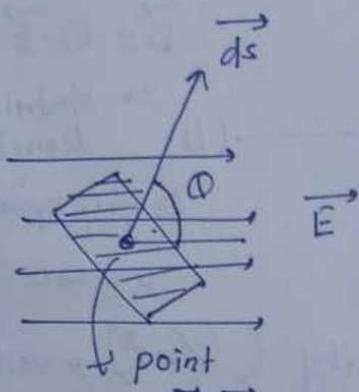


Maxwell's equation:

- its derived from Gauss law.

flux \rightarrow It is a measure of how much field lines passes through any surface.

\rightarrow Surface direction is always normal to the surface i.e perpendicular to the surface.



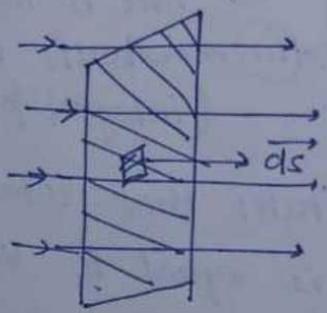
$d\psi = \vec{E} \cdot \vec{ds}$ \rightarrow flux for one point.

$\Psi = \int_s \vec{E} \cdot \vec{ds}$ \rightarrow flux through ^{all the} ~~whole~~ surface

$E \cdot ds = E ds \cos \theta$

$\theta = 0^\circ \rightarrow$ maximum value.

\Rightarrow When both the direction \vec{ds} and \vec{E} are same, then.



\vec{E} maximum field = maximum passing field flux will generate

$\theta = 0$
 $\cos 0^\circ = 1$
 so, maximum flux will generate.

$$\Psi = \int_s E \cdot ds \cos 0^\circ$$

$$= \int_s E \cdot ds$$

$\Psi = E \times \text{Area}$

(ii)

Gauss law :- it states that total electric flux passing through any close surface is equal to charge enclosed by closed surface, divided by ϵ_0 .

$$\oint_S \vec{E} \cdot d\vec{s} = \frac{Q_{\text{enclosed}}}{\epsilon_0} \quad \therefore \Phi = \text{flux} = \int \vec{E} \cdot d\vec{s}$$

$$\oint_S \epsilon_0 \vec{E} \cdot d\vec{s} = Q_{\text{enc}} \quad \therefore \vec{D} = \epsilon_0 \cdot \vec{E}$$

$$\oint_S \vec{D} \cdot d\vec{s} = Q_{\text{enc}} \quad \text{--- (i) electric flux Density,}$$

unit $\rightarrow \text{C/m}^2$

In free space

$$D = \epsilon_0 E$$

Let ρ_v be the volume charge density (C/m^3) \rightarrow volume

\rightarrow To find out the charge from the volume i.e.

$$Q = \int_V \rho_v dV \quad \text{--- (ii)}$$

From equation (i) and (ii)

$$\boxed{\oint_S \vec{D} \cdot d\vec{s} = \int_V \rho_v dV} \quad \rightarrow \text{This is nothing but the (iii) maxwell's 1st equation (integral form)}$$

\Rightarrow Divergence theorem :- it states that total flux passing through any closed surface is equal to volume integral of divergence of the vector

$$\oint_S \vec{D} \cdot d\vec{s} = \int_V (\nabla \cdot \vec{D}) dV \quad \rightarrow \text{(iv)}$$

From equation (iii) & (iv)

$$\int_V (\nabla \cdot \vec{D}) dV = \int_V \rho_v dV$$

$$\boxed{\nabla \cdot \vec{D} = \rho_v} \quad \rightarrow \text{(v)}$$

maxwell's 1st equation in (Differential form at point) form

(iii)

⊕

⇒ For source free region, (charge is zero)

$$\rho_v = 0$$
$$\boxed{\nabla \cdot \vec{D} = 0}$$

{ \vec{D} is a divergenceless if $\nabla \cdot \vec{D} = 0$ }
or Solenoid.

2nd maxwell's equation

conservative nature of electric field (for static)
(static means → field does not change w.r.t time)

done
Total work [^]to move a point charge around the closed loop in presence of electric field is always equal to zero.

$$\boxed{\oint_L \vec{E} \cdot d\vec{l} = 0}$$

maxwell's second (2nd) equation for static field.
(integral form) for static field

applying stoke's theorem.

Stokes theorem: A circulation of vector \vec{A} in a around the closed loop is equal to the surface integral of curl of that vector over the circle bounded by closed loop.

$$\oint_L \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) \cdot d\vec{s}$$

$$\int_S (\nabla \times \vec{E}) \cdot d\vec{s} = 0$$

$$\boxed{\nabla \times \vec{E} = 0}$$

Maxwell's 2nd equation, (in Differential form or point form)

Note: if the curl is zero, then its nothing but conservative field.

→ conservative in nature

Now, For Time Varying field :

— it comes from faraday's law.

Faraday's law:

it states that induced emf in a closed circuit is equal to time rate of change in flux linkage in the circuit.

$$V_{emf} = - \frac{d\lambda}{dt}, \quad \text{where}$$

$\lambda = \text{flux linkage (flux linking with no. of turns)}$
 $= N\psi$

$$V_{emf} = - \frac{Nd\psi}{dt}$$

$$\psi = \int_S \vec{B} \cdot d\vec{s}$$

$\vec{B} = \text{magnetic flux density.}$

unit = wb/m^2 or Tesla.

$\psi = \text{flux.}$

$D = \text{electric field Density}$
 $B = \text{magnetic field Density.}$

(Gai)

$$V_{emf} = -N \frac{d}{dt} \int_S \vec{B} \cdot d\vec{s} \quad \text{--- (1)}$$

Potential, $V = \oint_C \vec{E} \cdot d\vec{l} \quad \text{--- (2)}$

both this two equations are defining emf. so,

Therefore From eqⁿ (1) & (2) we can write.

$$\oint_C \vec{E} \cdot d\vec{l} = -N \frac{d}{dt} \int_S \vec{B} \cdot d\vec{s} \quad \text{--- (3)}$$

↳ Maxwell's ^{2nd} equation (integral form)
For time Varying.

applying stokes theorem; $\oint_C \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) \cdot d\vec{s}$

From (3) eqⁿ $\int_S (\nabla \times \vec{E}) \cdot d\vec{s} = -N \int_S \frac{d\vec{B}}{dt} \cdot d\vec{s}$

$$\nabla \times \vec{E} = -N \frac{d\vec{B}}{dt}$$

if $N=1$

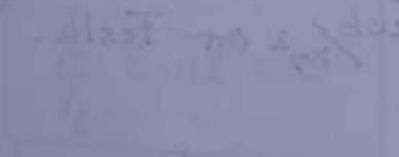
$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

→ Maxwell's 2nd eqⁿ for static field time varying field (differential form or point form)

$$\nabla \cdot \vec{E} = -\frac{\partial \rho}{\partial t}$$

$$\nabla \cdot \vec{B} = -N \frac{\partial \psi}{\partial t}$$

$\vec{B} = \text{magnetic flux density}$



$$\nabla \cdot \vec{E} = -N \frac{\partial \psi}{\partial t}$$

$$V = \oint \vec{E} \cdot d\vec{l} = -\frac{d\psi}{dt}$$

$$\oint \vec{E} \cdot d\vec{l} = -N \frac{d\psi}{dt}$$